

Chapter 7: Time Complexity

Time complexity

Let M be a deterministic Turing machine that halts on all inputs. The running time or *time complexity* of M is the function $f: N \rightarrow N$, where $f(n)$ is the maximum number of steps that M uses on any input of length n . If $f(n)$ is the running time of M , we say that

- M runs in time $f(n)$
- M is an $f(n)$ time Turing machine

Big-O notation

- Let f and g be functions $f, g: \mathbb{N} \rightarrow \mathbb{R}^+$.
 $f(n) = O(g(n))$ if positive integers c and n_0 exist such that for every integer $n \geq n_0$
$$f(n) \leq cg(n)$$

 $g(n)$ is an asymptotic upper bound for $f(n)$.

Small-o notation

- Let f and g be functions $f, g: \mathbb{N} \rightarrow \mathbb{R}^+$.
 $f(n) = o(g(n))$ if for every positive integer c ,
 n_0 exists such that for every integer $n \geq n_0$
$$f(n) < cg(n)$$

Time complexity class

$\text{TIME}(t(n)) = \{L \mid \exists \text{ TM } M \text{ s.t.}$

1) $L(M) = L$, and

2) \forall input w , M halts on w in $O(t(n))$ steps (language L is decided by an $O(t(n))$ time Turing machine)}

The class **P**

P is the class of languages that are decidable in polynomial time on a deterministic single-tape Turing machine. In other words,

$$\mathbf{P} = \bigcup_k \mathbf{TIME}(n^k)$$

Example 1: A language known to
be in **P**

$\text{CONN} = \{ \langle G \rangle \mid G \text{ is a} \\ \text{connected graph} \}$

Example 2: A language known to
be in **P**

$\text{PATH} = \{ \langle G, s, t \rangle \mid G \text{ is a graph, and } s, t \text{ are two vertices. There is a path from } s \text{ to } t. \}$

PATH is in P

A polynomial time algorithm M for PATH operates as follows:

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t .

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

Example 3: A language known
to be in **P**

Every context-free language is in P

Every CFL is in P

Let G be a CFG in CNF generating the CFL L . Assume that S is the start variable. A polynomial time algorithm D works as follows:

$D =$ “ On input $w = w_1 \dots w_n$:

1. If $w = \varepsilon$ and $S \rightarrow \varepsilon$ is a rule, accept.
2. For $i = 1$ to n :
3. For each variable A :
4. Test whether $A \rightarrow b$ is a rule, where $b = w_i$.
5. If so, place A in table (i, i) .
6. For $l = 2$ to n :
7. For $i = 1$ to $n-l+1$:
8. Let $j = i+l-1$,
9. For $k = i$ to $j-1$:
10. For each rule $A \rightarrow BC$:
11. If table (i, k) contains B and table $(k+1, j)$ contains C , put A in table (i, j) .
12. If S is in table $(1, n)$, *accept*. Otherwise, *reject*. “

Verifier

A **verifier** for a language A is an algorithm V , where

$$A = \{w \mid V \text{ accepts } \langle w, c \rangle \text{ for some string } c\}.$$

The time of a verifier is measured in terms of the length of w : $|w|$.

A **polynomial time verifier** runs in a polynomial time in the length of w . A language A is **polynomially verifiable** if it has a polynomial time verifier.

The class NP, definition

NP is the class of languages that have polynomial time verifiers.

HAMPATH = $\{ \langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t \}$ is in NP

Proof: the following is a NTM that decides HAMPATH problem in nondeterministic polynomial time.

HAMPATH= $\{ \langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t \}$ is in NP

N="On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Write a list of m numbers, p_1, \dots, p_m , where m is the number of nodes in G . Each number in the list is nondeterministically selected to be between 1 and m .
2. Check for repetitions in the list. If any are found, reject.
3. Check whether $s = p_1$ and $t = p_m$. If either fail, reject.
4. For each i between 1 and $m-1$, check whether (p_i, p_{i+1}) is an edge of G . If any are not, reject. Otherwise, all tests have been passed, so accept."

Theorem

Language L is in NP iff it is decided by some nondeterministic polynomial Time Turing machine.

Proof

(**→**) Let $A \in \text{NP}$ and A is decided by a polynomial time NTM N . Let V be the polynomial time verifier for A that exists by the definition of NP. Assume that V is a TM that runs in time n^k and construct N as follows:

$N =$ “On input w of length n :

1. Nondeterministically select string c of length at most n^k
2. Run V on input (w, c) .
3. If V accepts, accept; otherwise, reject.

Proof

(\longleftarrow) Assume that A is decided by a polynomial time NTM N and constructs a polynomial time verifier V as follows:

$N =$ “On input $\langle w, c \rangle$, where w and c are strings:

1. Simulate N on input w , treating each symbol of c as a description of the nondeterministic choice to make at each step.
2. If this branch of N 's computation accepts, accept; otherwise, reject.”

Time classes: **NTIME(f)**

NTIME(t(n)) = {L | L is a language
decided by an $O(t(n))$ time
nondeterministic Turing machine }

The class **NP**

$$\text{NP} = \bigcup_k \text{NTIME}(n^k)$$

Languages in NP

CLIQUE, SUBSET-SUM,
SAT, 3SAT, FACTOR, ISO,
VERTEX-COVER

$SAT = \{ \phi: \phi \text{ is a boolean formula that has a satisfying assignment} \}$

Polynomial verifier: guess assignment to variables, plug into ϕ , then verify

FACTOR = $\{ (k, N): N \text{ has a non-trivial factor less than } k \}$

Polynomial verifier:

- guess $1 < d < k$
- divide d by N
- determine whether the remainder is 0

Polynomial time computable function

- A function f is a polynomial time computable function if some polynomial time Turing machine M exists that halts with just $f(w)$ on its tape, when started on any input w .

Polynomial-time Reduction

A function $\mathbf{f} : \Sigma^* \rightarrow \Sigma^*$ is a polynomial-time reduction from language L_1 to language L_2 , $L_1 \leq_p L_2$, iff

- \mathbf{f} is a polynomial time computable function.
- for all w ,

$$w \in L_1 \iff \mathbf{f}(w) \in L_2$$

Theorem: If $A \leq_p B$ and $B \in P$, then
 $A \in P$

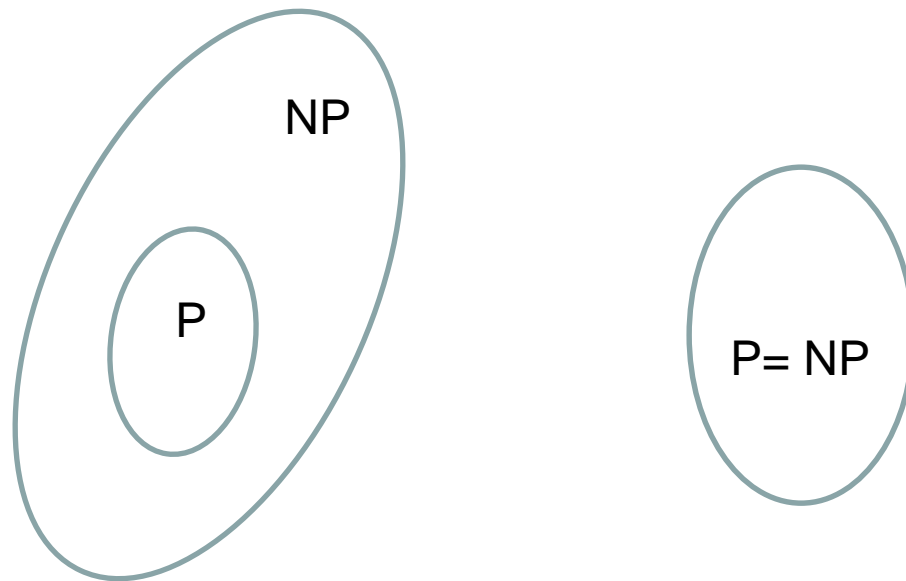
Proof:

Let M be the polynomial time algorithm deciding B and f be the polynomial time reduction from A to B . We describe a polynomial time algorithm N that decides A as follows.

$N =$ “On input w :

1. Compute $f(w)$.
2. Run M on input $f(w)$ and output whatever M outputs.”

P vs. NP



NP-hard

A language L is NP-hard
iff

$$\forall A \in \text{NP}, A \leq_p L$$

NP-complete

A language L is NP-complete
iff

- 1) $L \in NP$
- 2) L is NP-hard

The Cook-Levin Theorem: SAT is NP-complete

$SAT \in P$ iff $P = NP$

3-SAT

3-SAT = $\{ \phi(x_1, x_2 \dots x_n) \mid \phi \in \text{SAT},$
 $\phi = C_1 \text{ AND } C_2 \text{ AND } \dots C_n$
where $C_i = \alpha_{i1} \text{ OR } \alpha_{i2} \text{ OR } \alpha_{i3},$
and $\forall i, j \exists k: \alpha_{ij} = x_k \text{ or } \alpha_{ij} = \underline{x_k} \}$

Conjunctive Normal Form

3-SAT is NP-complete

Proof:

1) **3-SAT** \in **NP** (by guessing the assignment to variables

and verifying that $\phi(x_1, x_2 \dots x_n) = 1$)

2) $\forall L, L \in \text{NP } L \leq_p \text{3-SAT}$

Vertex Cover

Given graph $G = (V, E)$, a subset V_1 of vertices is a vertex cover if each edge in E is adjacent to at least one vertex in V_1

Vertex-Cover = $\{(G, k) \mid G \text{ has a vertex cover of size at most } k\}$

Directed Hamiltonian Path

Directed_HP = $\{(G,s,t) \mid G \text{ is a directed graph with a path that starts at vertex } s, \text{ ends at vertex } t, \text{ and visits every vertex of } G \text{ exactly once}\}$

CLIQUE

CLIQUE = $\{ \{ (G, k) \mid \exists S, S \subseteq V_G, \text{ s.t. } |S| = k, \text{ and } S \text{ is fully connected inside } G \}$

SUBSET_SUM

SUBSET_SUM = $\{(A, k) \mid A \text{ is a set (list) of integers, s.t. } \exists B: B \subseteq A \text{ where } \sum_{w \in B} w = k\}$

Reference

- www.cs.unm.edu/~gemmell/500.html by Dr. Peter Gemmell.